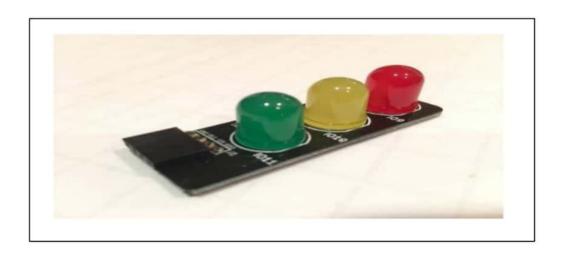
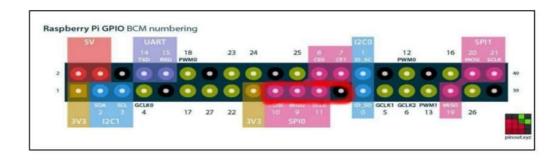
Experiment no -8 Aim &- write an application using Raspberry - Pil beagle board to Control operation of a hordware simulated traffic signal Theory :-Attaching traffic Lights :-The low voltage labs traffic lights connect to Pi wing four pins. one of trese needs to be ground, he tree three being actual GPZo pins used to control each of individual LED's. Programming the traffic lights :-You need to install a couple of extra software packages needed to allow you to download sample cade + to give python access to GPTO pins on Pi. sudo apt-get install python-der python-rpi gpio git How it works : The code for this is very simple. it starts by importing Rpi GPZO library, plus time which gives us a fined wait function, signal that allows us to trap signal sent when user tries to quit program import RPi. GPTO as GPTO import time inport signal import sys





setup &-GPTO. setmode (GPTO. BLM) GPTO set mode up (9, GPTO.OUT) CPIO setup (10, GPIO OUT) GPIO. setup (11, GPIO. OUT) the main part of program will run in infinite (oup until user exit, by Stopping python with ctric It's a good idea to add handler tunn that will run whenever this happens so that we can turn off all lights prior to existing. # Turn off all lights when were ends demo def all Lights off (signal, frame): GPTO. output (3, false) GPIO. OY tPYT (10, false) GPZO. output (11, false) GPTO (lean Up () Sys exit(0) Signal . Signal (Signal . STGINT, allligh toff) The main body of code then consists of intinite while loop but turns on 4d light, waits, turn on ambee light, waits then cycles through rest of traffic light pattern by turning appropriate LEO's on 4 off: Conclusion :-Thus, we have implemented application for traffic signals using Rospberry Pi